WEST Search History

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DATE: Tuesday, March 10, 2009

Hide?	**Set Name**	**Query**	**Hit Count**
		DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ	
☐	L71	L70 and L67	188
☐	L70	(700/245 l700/250 l700/251 l700/254 l700/257 l700/264 l700/275 or 600/101 l600/102 l600/103 l600/104 l600/118 l600/424 l600/427 l600/429 or 606/1.130 or 901/1 l901/2 l901/8 l901/9 l901/30 l901/33 l901/34).ccls.	9108
☐	L69	(robot$6 or articulat$3 or automat$6 or autonomous$2 or CNC or machine $2 or mechanical device or mechan$6 or servomechan$4) and (sugery or davinci or endoscopic or laparoscopic or robosurgeon or haptic or telepresesence or telesurgery or virtual reality or zeus) and (handle or manipulator)	17034
☐	L68	('6718233' l'6701220' l'6681151' l'6675070' l'6675069' l'6587749' l'6522949' l'6434449' l'6430473' l'6321137')!.ABPN1,NRPN,PN,TBAN, WKU.	24
☐	L67	marc.xa. and robot and manipulator	194
☐	L66	('6728598' l'6650965' l'6381515' l'6668211' l '6505097' l'6718232' l'6470237' l '6321140')!.ABPN1,NRPN,PN,TBAN,WKU.	13
☐	L65	('6594552' l'6587750' l'6470236')!.ABPN1,NRPN,PN,TBAN,WKU.	6
☐	L64	marc.xa. and robot and manipulator and medical	37
☐	L63	(trasmission or gear$3 or mesh or toothed machine part) same (chang$3 or shift$3 or switch$3) and (speed or accelerat$4 or velocity) and (motor vehicle or car or van or train or airplane or automobile) and detect$6	24319
☐	L62	robot$6 and (walk$3 or biped or humanoid or two legged) and (inlina$6 or betn or tilt or deviat$5 or obliqu$5 or indirect$4 or change direction or slope or slant)	6259
☐	L61	('6711469' l'6697709' l'6567724' l'6505098' l'6493606' l'6480761' l'6330494' l'6289265' l'6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	16
☐	L60	marc.xa. and legged and inclination	35
☐	L59	marc.xa. and legged and inclinaiton	0
☐	L58	('5404086')!.ABPN1,NRPN,PN,TBAN,WKU.	2

☐	L57	(edditing or updating) and (motion or traject$4 or movement) and zmp and robot$6	26
☐	L56	(edditing or updating) same (motion or traject$4 or movement) and zmp and robot$6	11
☐	L55	(edditing or updating) same (motion or traject$4 or movement) and L54	10
☐	L54	robot and zmp and yaw	168
☐	L53	marc.xa. and zmp	47
☐	L52	10/181500	3
☐	L51	('6697709' I'6289265' I'6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	6
☐	L50	marc.xa. and robot and zmp	47
☐	L49	(motions or movement or displacement) and L48	122
☐	L48	computer and L47	135
☐	L47	record$3 and L46	135
☐	L46	(request or command) and L45	166
☐	L45	L41 and L44	174
☐	L44	execut$5 and L43	310768
☐	L43	run or L41	1384705
☐	L42	(6458772 or 6284156 or 6348461 or 6262044 or 6410586 or 6342245 or 6277877 or 6399557 or 3857856 or 5835892 or 6376445 or 6440911 or 6163111 or 5610305 or 5230889 or 4391489 or 4483594 or 6410749 or 4876009 or 6358945 or 6281227 or 6391397 or 6432994 or 4920120 or 5874378 or 6374641 or 5384779 or 5523998 or 5537098 or 4260406 or 4293439 or 4386503 or 5179438 or 5208607 or 6275216 or 5534261 or 5640119 or 5831440 or 6049212 or 6271251 or 4949326 or 5015815 or 5194938 or 4870247 or 6258470 or 6316465 or 6388989 or 4505827 or 5210848 or 5230070).pn.	98
☐	L41	(similar or "same") function and L40	201
☐	L40	robot and control software and (chang$3 or replac$5)	2153
☐	L39	('20050125099')!.ABPN1,NRPN,PN,TBAN,WKU.	2
☐	L38	(10/126774 I 10/970977 I 10/935607 I 10/919172 I 10/775845 I 10/732446 I 10/726597 I 10/683496 I 10/637890)	18
☐	L37	robot$6 and (walk$3 or biped or humanoid or two legged) and (inlina$6 or betn or tilt or deviat$5 or obliqu$5 or indirect$4 or change direction or slope or slant)	6259

☐	L36	('6711469' l'6697709' l'6567724' l'6505098' l'6493606' l'6480761' l'6330494' l'6289265' l'6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	16
☐	L35	marc.xa. and legged and inclination	35
☐	L34	marc.xa. and legged and inclinaiton	0
☐	L33	('5404086')!.ABPN1,NRPN,PN,TBAN,WKU.	2
☐	L32	(edditing or updating) and (motion or traject$4 or movement) and zmp and robot$6	26
☐	L31	(edditing or updating) same (motion or traject$4 or movement) and zmp and robot$6	11
☐	L30	(edditing or updating) same (motion or traject$4 or movement) and L29	10
☐	L29	robot and zmp and yaw	168
☐	L28	marc.xa. and zmp	47
☐	L27	10/181500	3
☐	L26	('6697709' l'6289265' l'6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	6
☐	L25	marc.xa. and robot and zmp	47
☐	L24	(motions or movement or displacement) and L23	122
☐	L23	computer and L22	135
☐	L22	record$3 and L21	135
☐	L21	(request or command) and L20	166
☐	L20	L16 and L19	174
☐	L19	execut$5 and L18	310768
☐	L18	run or L16	1384705
☐	L17	(6458772 or 6284156 or 6348461 or 6262044 or 6410586 or 6342245 or 6277877 or 6399557 or 3857856 or 5835892 or 6376445 or 6440911 or 6163111 or 5610305 or 5230889 or 4391489 or 4483594 or 6410749 or 4876009 or 6358945 or 6281227 or 6391397 or 6432994 or 4920120 or 5874378 or 6374641 or 5384779 or 5523998 or 5537098 or 4260406 or 4293439 or 4386503 or 5179438 or 5208607 or 6275216 or 5534261 or 5640119 or 5831440 or 6049212 or 6271251 or 4949326 or 5015815 or 5194938 or 4870247 or 6258470 or 6316465 or 6388989 or 4505827 or 5210848 or 5230070).pn.	98
☐	L16	(similar or "same") function and L15	201
☐	L15	robot and control software and (chang$3 or replac$5)	2153
☐	L14	('20050125099')!.ABPN1,NRPN,PN,TBAN,WKU.	2

☐	L13	(10/126774 I 10/970977 I 10/935607 I 10/919172 I 10/775845 I 10/732446 I 10/726597 I 10/683496 I 10/637890)	18
☐	L12	invasive and L11	57
☐	L11	surgery and L10	80
☐	L10	L4 or L8	412
☐	L9	L4 and L8	0
☐	L8	phillip.in. and robot	307
☐	L7	(green, S. phillip).in. and robot	0
☐	L6	(green S. phillip).in. and robot	0
☐	L5	green phillip.in. and robot	0
☐	L4	green.in. and robot	105
☐	L3	phillips.in. and robot	307
☐	L2	greene.in. and robot	29
☐	L1	10/738359	2

END OF SEARCH HISTORY